

# Applications of generalized coherent states in Bose-Hubbard model

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# Overview

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**1. Bose-Hubbard model**

**2. Generalized coherent state**

**3. Time-dependent variational principle**

# Bose-Hubbard model

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$$\hat{H} = -J \sum_{\langle i,j \rangle} (a_i^\dagger a_j + \text{h.c.}) + \frac{U}{2} \sum_{i=1}^M a_i^{\dagger 2} a_i^2,$$

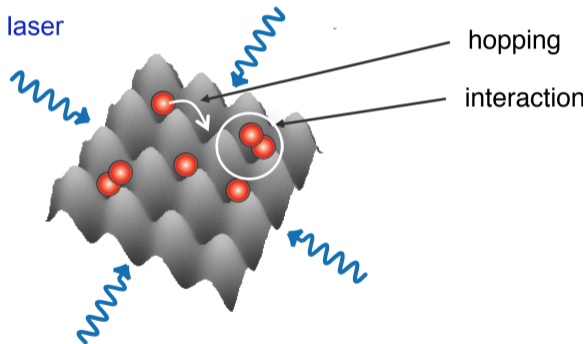


Figure is from Peter Zoller's talk

# Bose-Hubbard model

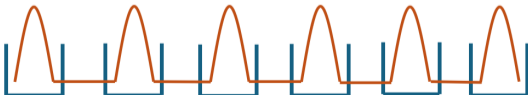
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Phase transition of ground state depends on the **ratio**:  $\frac{U}{J}$

for  $U/J \rightarrow \infty$ ,  $|\text{GS}\rangle = \prod_{i=1}^M a_i^\dagger |0\rangle = |11 \cdots 1\rangle$  ( $M$  is equal to number of particles  $S$ )



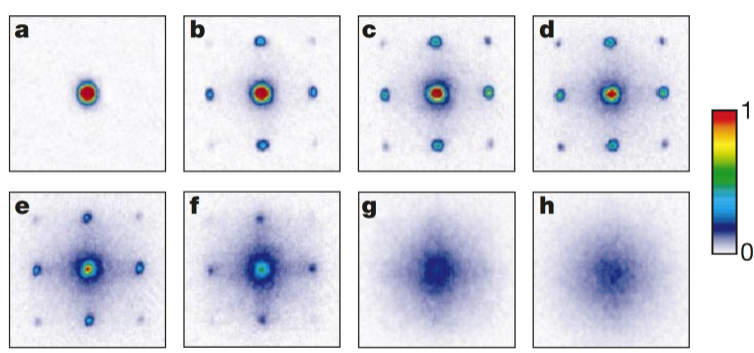
for  $U/J \rightarrow 0$ ,  $|\text{GS}\rangle = \frac{1}{\sqrt{S!}} \left( \sum_{i=1}^M \frac{1}{\sqrt{M}} a_i^\dagger \right)^S |00 \cdots 0\rangle = \frac{1}{\sqrt{S!}} \left( b_{p=0}^\dagger \right)^S |0\rangle$



# Bose-Hubbard model

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Phase transition from superfluid to Mott insulator:



M. Greiner, et al., Nature 415, 39–44 (2002)

# Generalized coherent state (GCS)

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$$|S, \xi\rangle = \frac{1}{\sqrt{S!}} \left( \sum_{i=1}^M \xi_i \hat{a}_i^\dagger \right)^S |\text{vac}\rangle, \quad S: \text{number of particles}, M: \text{number of modes/sites}$$

$$\xi = \{\xi_1, \xi_2, \dots, \xi_M\}, \quad \text{normalization condition: } \sum_{i=1}^M |\xi_i|^2 = 1$$

$$\hat{b}^\dagger = \sum_{i=1}^M \xi_i \hat{a}_i^\dagger, \quad |S, \xi\rangle = \frac{1}{\sqrt{S!}} (\hat{b}^\dagger)^S |\text{vac}\rangle: \text{condensate}$$

$$\text{Example: } |2, \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\rangle = \frac{1}{2}|20\rangle + \frac{1}{\sqrt{2}}|11\rangle + \frac{1}{2}|02\rangle$$

**P. Buonsante and V. Penna, J. Phys. A: Math. Theor. 41, 175301 (2008)**

# Relationship between two ground states

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$$|11\cdots 1\rangle = \sum_{k=1}^N A_k |S, \xi_k\rangle, \quad N = 2^{S-1}$$

Simple equation:  $x_1 x_2 = \frac{1}{4}(x_1 + x_2)^2 - \frac{1}{4}(x_1 - x_2)^2$

general case:  $x_1 x_2 \cdots x_M \rightarrow$  Kan's formula

Single parameterized state can not describe the phase transition

**R. Kan, J. Multivar. Anal. 99, 542 (2008).**

**Y. Q, J. Huh and F. Grossmann, SciPost Phys. 15, 007 (2023)**

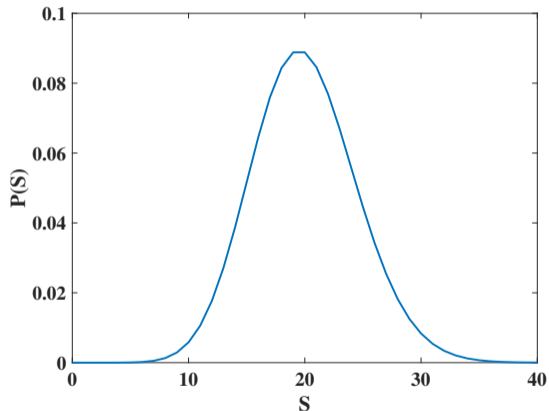
# GCS / Glauber coherent state

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$$|\vec{\alpha}\rangle = e^{-\frac{1}{2}\sum_{i=1}^M |\alpha_i|^2} e^{\sum_{i=1}^M \alpha_i \hat{a}_i^\dagger} |0, 0, \dots, 0\rangle$$

$$= \sum_{S=0}^{\infty} \sqrt{P(S)} |S, \vec{\xi}\rangle$$

$$\tilde{N} = \sum_{i=1}^M |\alpha_i|^2, \quad P(S) = e^{-\tilde{N}} \frac{\tilde{N}^S}{S!}$$





# GCS / Glauber coherent state

Multi-mode Glauber coherent state	generalized coherent state
$ \alpha\rangle = \prod_{i=1}^M e^{-\frac{ \alpha_i ^2}{2}} e^{\alpha_i \hat{a}_i^\dagger}  \text{vac}\rangle = \otimes_{i=1}^M  \alpha_i\rangle$	$ S, \xi\rangle = \frac{1}{\sqrt{S!}} \left( \sum_{i=1}^M \xi_i \hat{a}_i^\dagger \right)^S  \text{vac}\rangle$
$a_i  \alpha\rangle = \alpha_i  \alpha\rangle$	$\hat{a}_i  S, \xi\rangle = \sqrt{S} \xi_i  S-1, \xi\rangle$
$\langle \alpha   \hat{a}_i^\dagger a_j   \alpha \rangle = \alpha_i^* \alpha_j$	$\langle S, \xi   \hat{a}_i^\dagger \hat{a}_j   S, \xi \rangle = S \xi_i^* \xi_j$
$\langle \alpha   \beta \rangle = \exp \left[ \sum_{i=1}^M \alpha_i^* \beta_i - \frac{1}{2} ( \alpha_i ^2 +  \beta_i ^2) \right]$	$\langle S', \xi   S, \eta \rangle = \left( \sum_{i=1}^M \xi_i^* \eta_i \right)^S \delta_{S, S'}$
overcomplete in whole Hilbert space	overcomplete in S-particle subspace

# Time-dependent variational principle

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Initial state:  $|\psi(t=0)\rangle = |S, \xi\rangle$

ansatz:  $|\psi(t)\rangle = \sum_{k=1}^N A_k(t) |S, \xi_k(t)\rangle$ ,  $N$ : multiplicity.

- GCS serve as overcomplete bases
- $N = 1$ :  $i\dot{\xi}_i = -J(\xi_{i+1} + \xi_{i-1}) + U(S-1)|\xi_i|^2 \xi_i$
- $N > 1$  is beyond mean-field result if  $\langle S, \xi_k | S, \xi_{k'} \rangle \neq 0$

**Y. Q and F. Grossmann, Phys.Rev.A 103, 042209 (2021)**

# Time-dependent variational principle

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Parameterized ansatz:  $|\psi(\mathbf{x})\rangle = |\psi(x_1, x_2, \dots, x_M)\rangle$ ,  $\mathbf{x} = \{A, \xi\}$

Schrodinger equation:  $\partial_t |\psi(\mathbf{x})\rangle \approx -i\hat{H}|\psi(x)\rangle$

Left side:  $\partial_t |\psi(\mathbf{x})\rangle = \dot{x}^\nu |V_\nu\rangle$ ,  $|V_\nu\rangle = \partial_{x_\nu} |\psi\rangle$

Right side:  $-i\hat{H}|\psi(x)\rangle$

Best approximation:  $\langle V_\mu | V_\nu \rangle \dot{x}^\nu = -i \langle V_\mu | \hat{H} | \psi(x) \rangle$

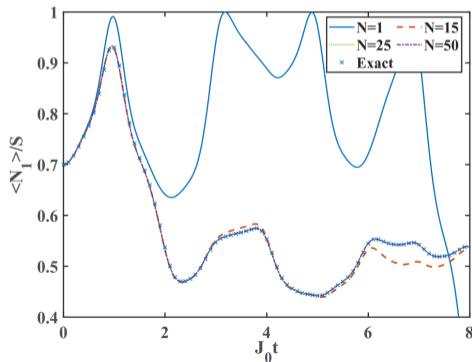
**L. Hackl, et al., SciPost Phys. 9, 048 (2020).**

# Nonequilibrium dynamics

Two-site mode:

$$H = -J(t)(\hat{a}_1^\dagger \hat{a}_2 + \hat{a}_2^\dagger \hat{a}_1) + \frac{U}{2}(\hat{a}_1^{\dagger 2} \hat{a}_1^2 + \hat{a}_2^{\dagger 2} \hat{a}_2^2), \quad J(t) = J_0 + J_1 \cos(\omega t)$$

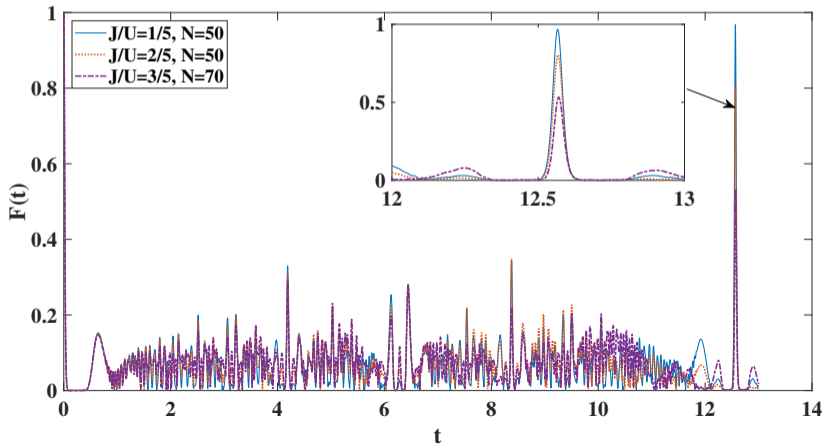
initial state:  $|S = 50, \xi_1 = -\sqrt{0.7}, \xi_2 = \sqrt{0.3}\rangle$



# Nonequilibrium dynamics

Considering initial state:  $|\vec{\alpha}\rangle = |\sqrt{20}, 0, \sqrt{20}, 0\rangle$  with  $\tilde{N} = 40$ , if  $J = 0$ ,  $T = \frac{2\pi}{U}$

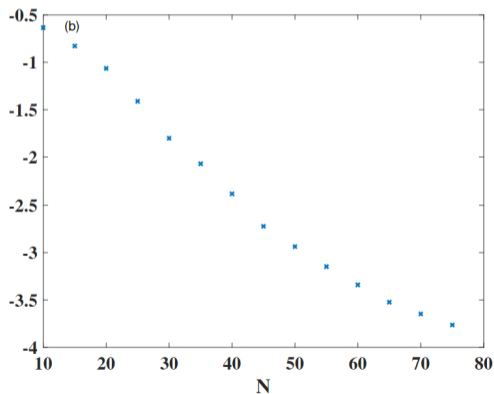
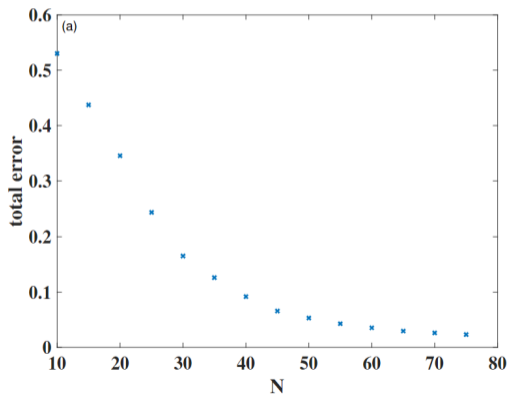
$F(t) = |\langle \vec{\alpha} | e^{-i\hat{H}t} | \vec{\alpha} \rangle|$ , S. Tomsovic, et al, Phys.Rev.A, 2018, 97(6)



# Nonequilibrium dynamics

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Accumulated error:  $E = \int_0^t d\tau |F_{\text{GCS}}(\tau) - F_{\text{exact}}(\tau)|$



# Outlook

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Linear combination of GCS for

1. Extended BH model/time-dependent Hamiltonian/...
2. Scrambling of quantum information (OTOC)
3. Fermi systems .....