

02/17/2021 VISTA

Quantum dynamics with the quantum trajectory-guided adaptable Gaussian bases

Sophya Garashchuk

Dept of Chemistry & Biochemistry

University of South Carolina, Columbia, USA



Outline

1. Time-dependent Gaussians
2. Quantum trajectory dynamics
3. QT-driven GBFs for exact dynamics
4. Examples
5. Summary

quantum dynamics ~ quantum nuclei

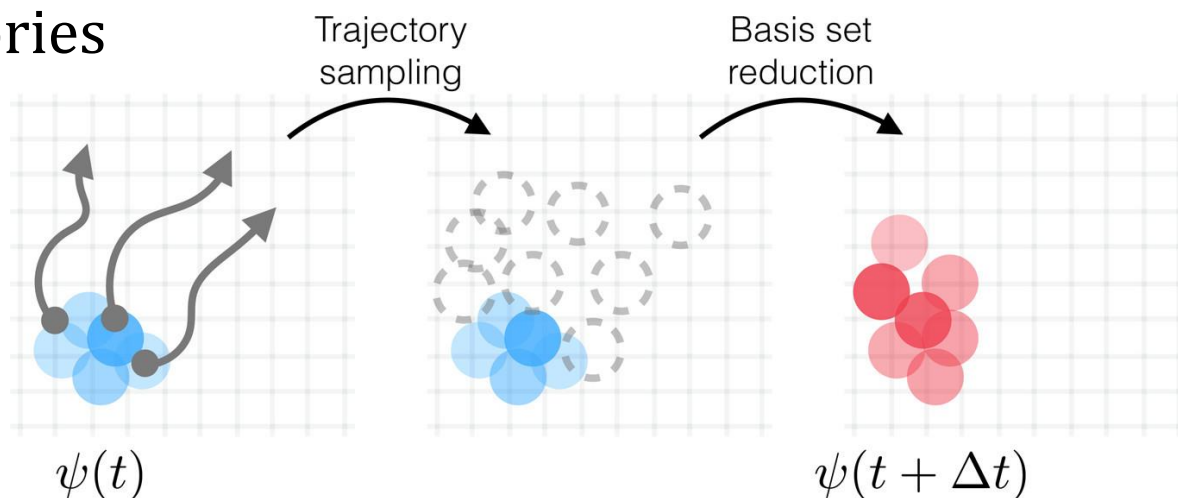
$$H(t)|\psi(t)\rangle = i\hbar\frac{\partial}{\partial t}|\psi(t)\rangle$$

- The complexity and size of WF scale **exponentially**
- Space-fixed grids/bases are inefficient for large amplitude motion
- Use time-dependent bases, representations, trajectories adaptable to WF
- Include some physics of a system, e.g. mass, energy and time-scale separation
- Factorization or layers for WFs
- Want time-dependent means to solve the TDSE

trajectory-guided (and related) basis functions

Gaussian basis functions GBFs (often taken as ‘frozen’)

- Variational Multiconfigurational Gaussians
- Coupled Coherent Gaussians (classical trajectories)
- Full multiconfiguration spawning
- Multiconfiguration Ehrenfest, cloning
- GBF reexpansions -- basis set leaping, matching pursuit, exploratory trajectories



Why Gaussians?

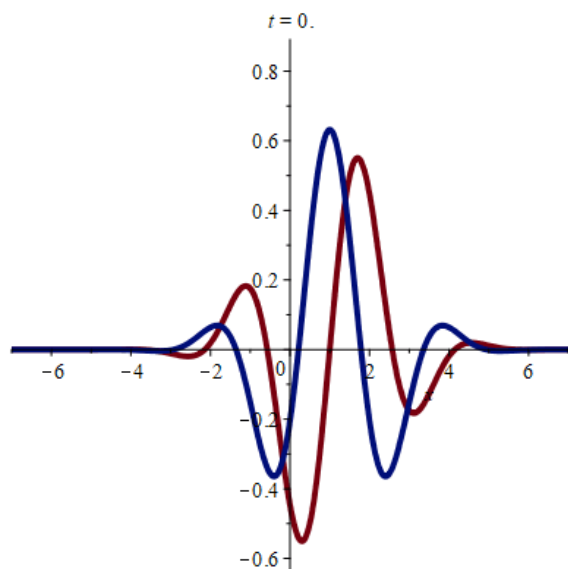
Thawed Gaussians solve TDSE for locally harmonic potentials

complex A

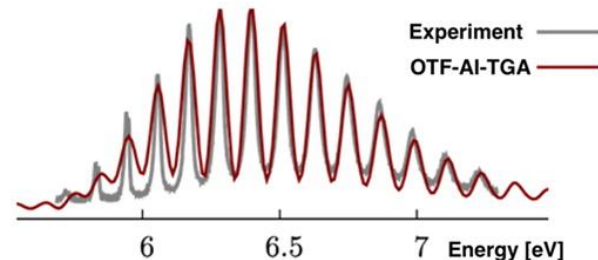
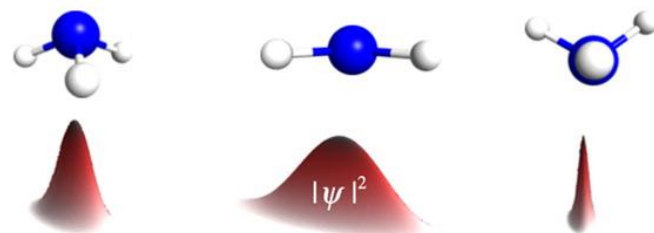
$$\psi(x, t) = \mathcal{N} \exp \left(-(x - q_t)^T \mathbf{A}_t (x - q_t) + i p_t^T (x - q_t) + i s_t + \gamma_t \right)$$

$$\frac{dq}{dt} = \mathbf{M}^{-1} p, \quad \frac{dp}{dt} = -\nabla V(q) \quad i \frac{d\mathbf{A}}{dt} = 2\mathbf{A}\mathbf{M}^{-1}\mathbf{A} - \frac{1}{2}\mathbf{V}_2, \quad \frac{d\gamma}{dt} = \text{Tr}(\mathbf{A}_{\Im}\mathbf{M}^{-1})$$

$$\frac{ds}{dt} = \frac{p^T \mathbf{M}^{-1} p}{2} - V(q) - \text{Tr}(\mathbf{A}_{\Re}\mathbf{M}^{-1})$$

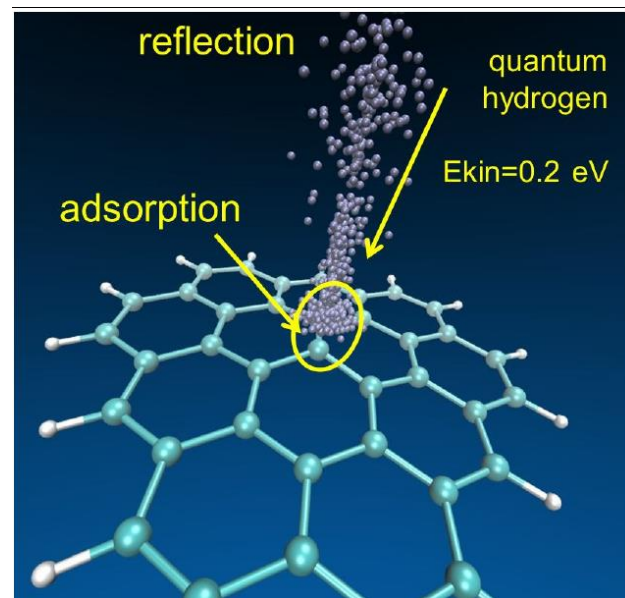


On-the-fly *ab initio* thawed Gaussian wave packet propagation



Why (quantum) trajectories?

- Nuclei are nearly classical; CM scales linearly
- Trajectory framework is convenient for mixed representations
- The QT formulation has classical and quantum ‘regimes’
- **Approximate** implementation gives cheap estimates of the dominant QM effects
- QTs define an ideal ‘grid’ in coordinate space

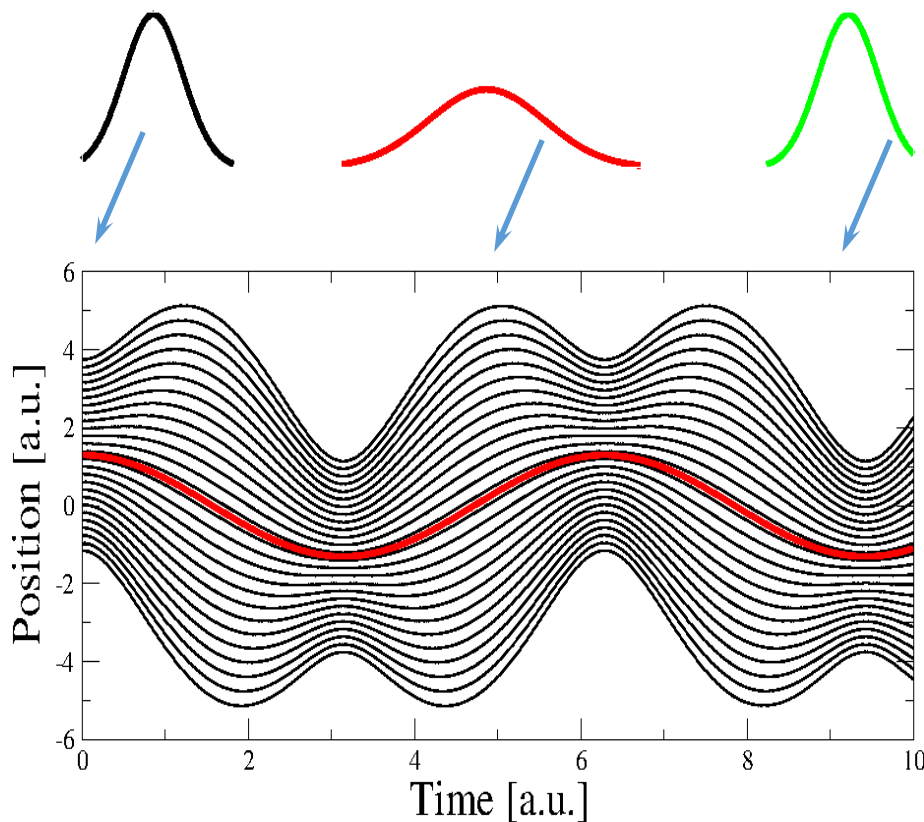


WF $\psi = |\psi| e^{is(x,t)}$

QT $(q,p) \quad p := \nabla(\arg \psi)|_{x=q}, \quad \frac{dq}{dt} = \frac{p}{m}$

$$\frac{dp}{dt} = -\nabla(V + U)|_{x=q}$$

$$\frac{ds}{dt} = \frac{\mathbf{p} \cdot \mathbf{p}}{2m} - (V + U)|_{x=q}$$



$$U = -\frac{\hbar^2}{2m} \frac{\nabla^2 |\psi|}{|\psi|}$$

quantum potential

Continuity of $\rho = |\psi(x, t)|^2$

$$\frac{d\rho}{dt} = -\frac{\nabla p}{m} \rho$$

$|\psi|^2 \delta x$ along a QT is constant

QT-guided adaptable Gaussian Bases (QTAG)

$$\psi(x, t) = \sum_{j=1}^{N_b} c_j(t) g_j(x, t) \quad \text{WF expansion in GBFs}$$

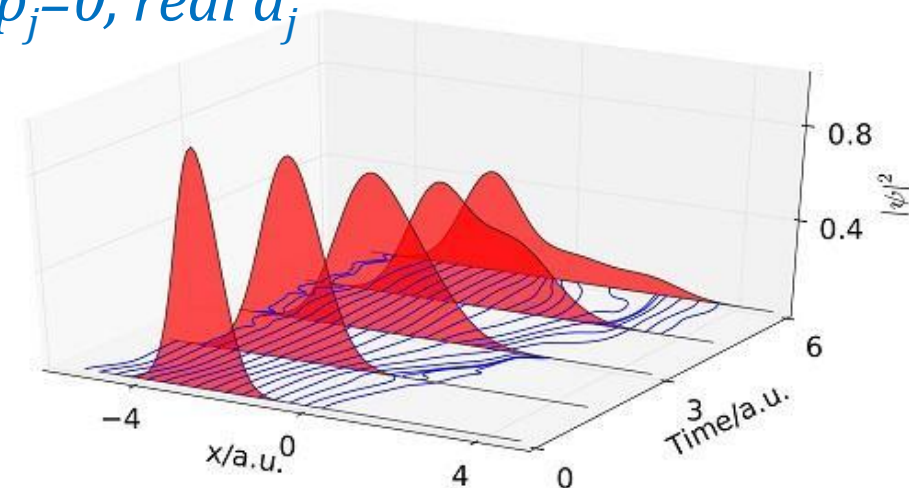
$$g_j := g_j(x; \vec{\lambda}_j(t)) = \left(\frac{a_j}{\pi}\right)^{1/4} \exp\left(-\frac{a_j}{2}(x - q_j)^2 + ip_j(x - q_j) + is_j\right)$$

$$\mathbf{\Lambda} \equiv \langle \vec{g} \times | \left(\hat{H} - i \frac{\partial}{\partial t} \right) \vec{g} \rangle, \quad \mathbf{S} = \langle \vec{g} \times \vec{g} \rangle, \quad \mathbf{\Lambda} \vec{c} = i \mathbf{S} \frac{d\vec{c}}{dt}$$

GBF parameters $\vec{\lambda}_j(t) = (a_j, q_j, p_j, s_j)^T$

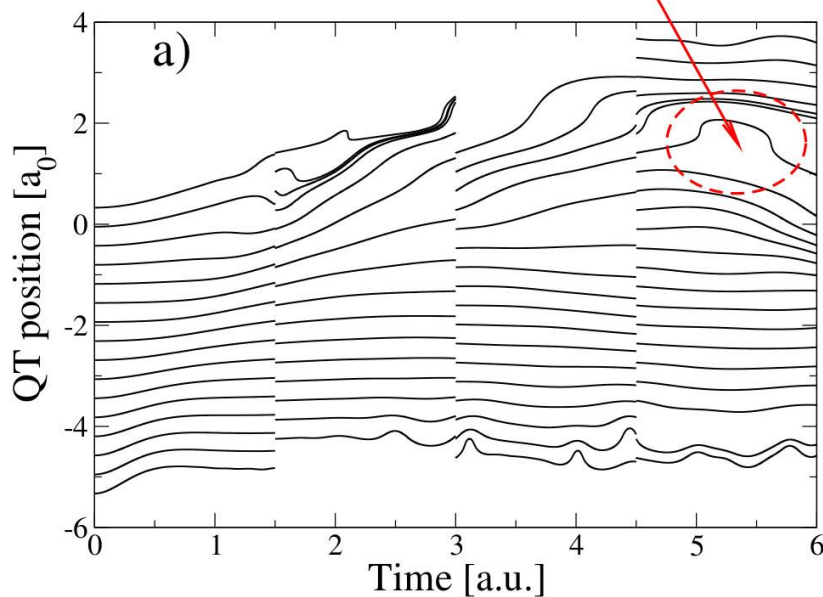
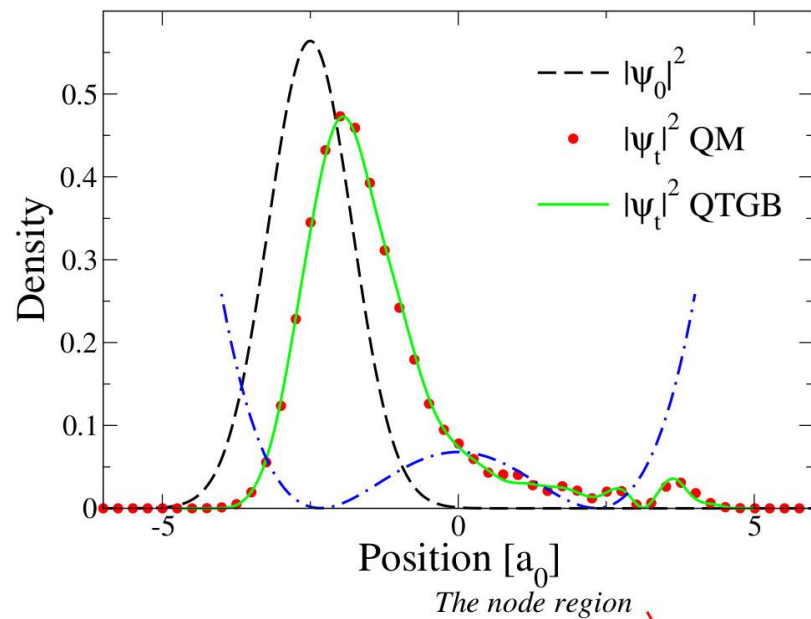
(i) use **real frozen GBFs**: $s_j=0$, $p_j=0$, *real* a_j

(ii) no quantum force



$$\frac{dq}{dt} = \frac{p}{m}, \quad p = \Im \left(\frac{\nabla \psi}{\psi} \right)$$

1D double well



2D $V_b=0.6366$ [frequency]

Basis N	10	12	16	QM
a [a.u.]	16	16	32	512 pnt
n=0	.4827	.4822	.4830	.4829
n=1	.7110	.7180	.7209	.7163

Convolved WF for smoother \mathbf{p}
 (don't need perfect QTs after all)

Re-expansion for stability and basis size adjustment

Basis degeneracy if GBFs are close
 (want adaptable GBFs)

QTs 'optimize' the basis in coordinate space w/out solving the variational eqs
 Relation to the fully variational basis?

general variational GBF time-dependence

$$\epsilon = \int_{x \in \mathbf{R}} \left| \hat{H} \psi - \imath \partial \psi / \partial t \right|^2 dx \quad \mathbf{S} := \text{GBF overlaps}$$

$\mathbf{I} :=$ unit matrix

$$\mathbf{B} \frac{d}{dt} \boxed{\vec{\Lambda}} = \vec{Y} \quad \mathbb{I} := |\vec{g}\rangle \mathbf{S}^{-1} \langle \vec{g}| \quad \text{resolution of identity in a basis}$$

$$B_{j\alpha, l\beta} = \Re (\rho_{jl} [\langle \partial \vec{g}_\alpha \otimes | \mathbf{I} - \mathbb{I} | \otimes \partial \vec{g}_\beta \rangle]_{jl}) \quad \rho_{jl} := c_j^* c_l$$

$$Y_{j\alpha} = \Im \left(\sum_l \rho_{jl} \left[\left\langle \partial \vec{g}_\alpha \otimes | \mathbf{I} - \mathbb{I} | \otimes \hat{H} \vec{g} \right\rangle \right]_{jl} \right)$$

$\mathbf{I} - \mathbb{I}$ subspace complementary to that covered by the basis

if the basis is good the variational equations are singular

instead consider solution when *each* GBF solves TDSE
 GBF is localized on a scale of LHA and WF

$$\imath \sum_{\beta} \partial g_{l\beta} \dot{\lambda}_{l\beta} = \hat{H} g_l \quad \text{Thawed Gaussian, } \textit{real } a_t$$

$$g(x, t) = \left(\frac{a_t}{\pi}\right)^{1/4} \exp\left(-\frac{a_t}{2}(x - q_t)^2 + \imath \mathcal{S}(q_t) + \imath \mathcal{S}'(q_t)(x - q_t) + \frac{\imath \mathcal{S}''(q_t)}{2}(x - q_t)^2\right)$$

TDSE gives

$$\dot{q}_j = \frac{p_j}{m}, \quad \dot{a}_j = -\frac{2a_j}{m} \nabla p_j, \quad \dot{s}_j = \frac{p_j^2}{2m} - V(q_j) - U(q_j)$$

variational

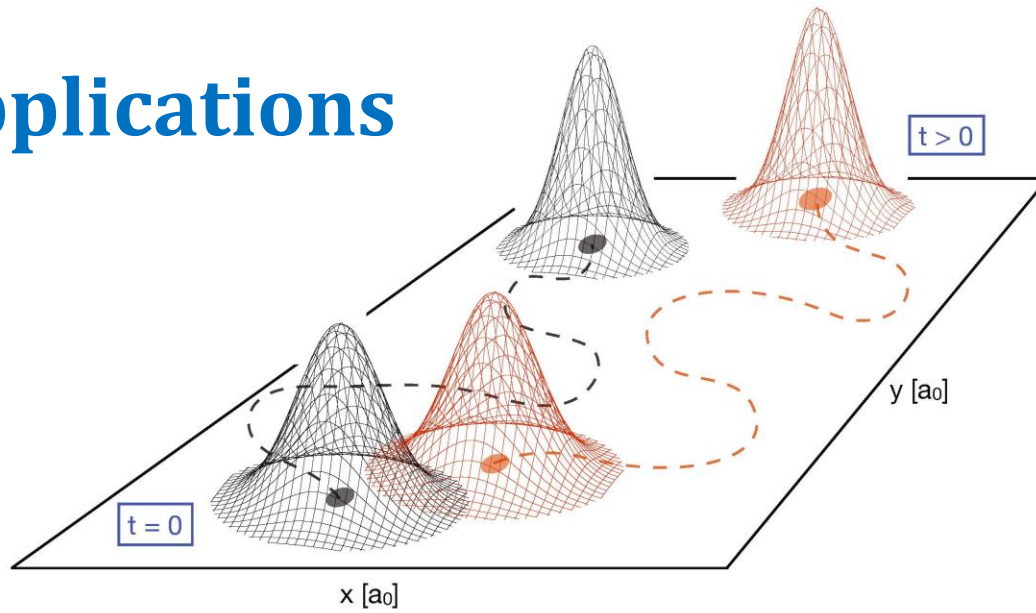
optional phase

p_j and $U(q_j)$ from

$$z_j := \left. \frac{\nabla \psi(x, t)}{\psi(x, t)} \right|_{x=q_t}$$

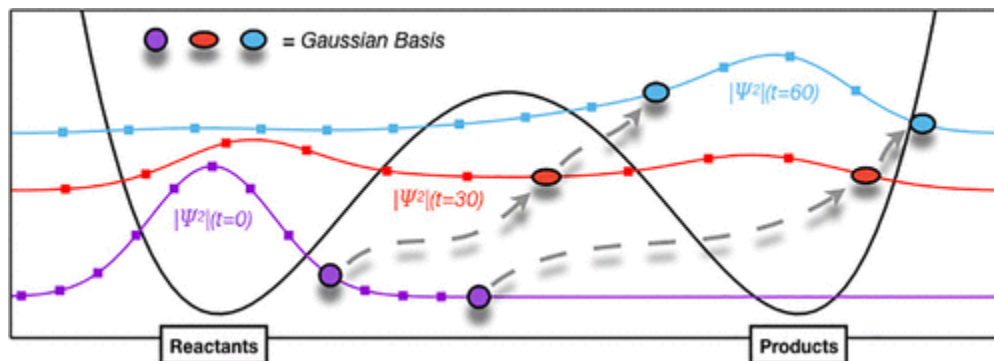
$$c_j \text{ from} \quad \mathbf{\Lambda} \equiv \langle \vec{g} \times | \left(\hat{H} - \imath \frac{\partial}{\partial t} \right) \vec{g} \rangle, \quad \mathbf{S} = \langle \vec{g} \times \vec{g} \rangle, \quad \mathbf{\Lambda} \vec{c} = \imath \mathbf{S} \frac{d\vec{c}}{dt}$$

applications



Accuracy: energy and norm conservation

Output: auto- and cross-correlations, $C(t) = \langle \psi(0) | \psi(t) \rangle$, and spectra

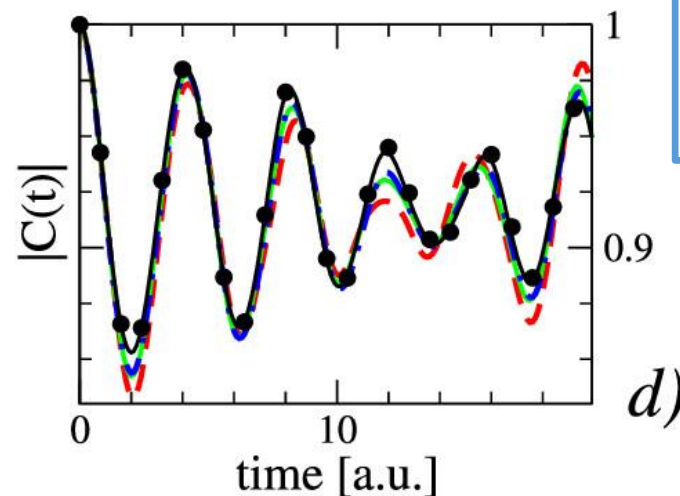
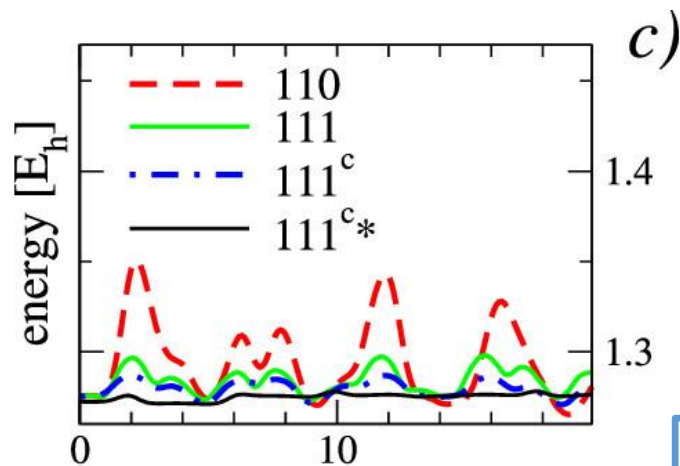
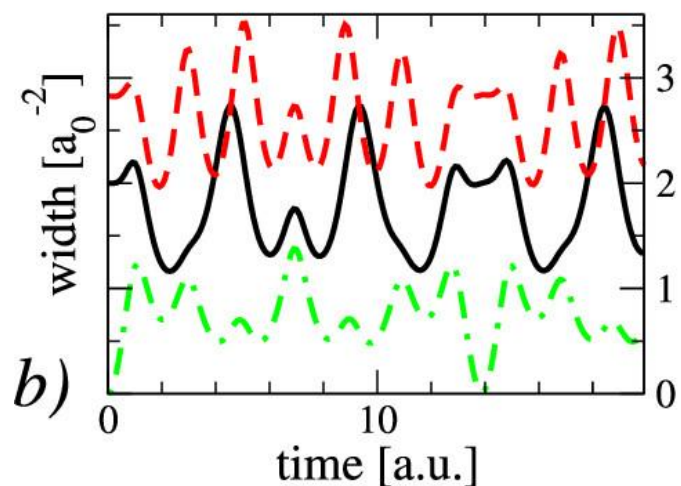
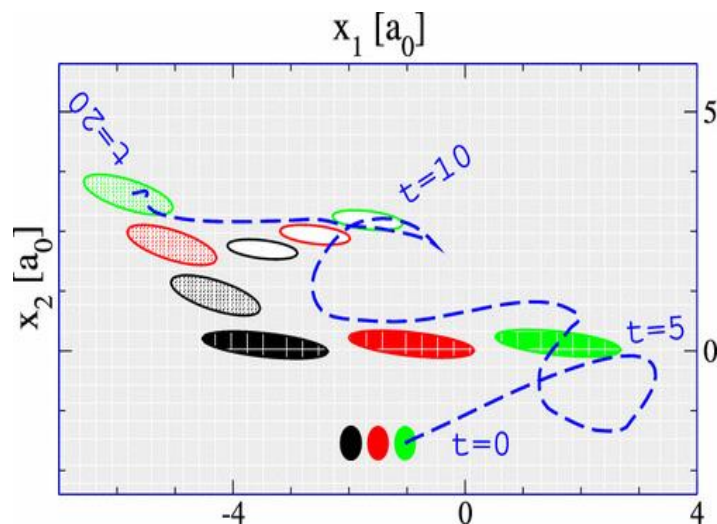


Positions of 3 GBFs : the oval size represents the GBF localization

coupled H0 model

44 GBFs; * = 57 GBFs; circles = SOFT

1/0 = adapted/fixed (q,p,a)

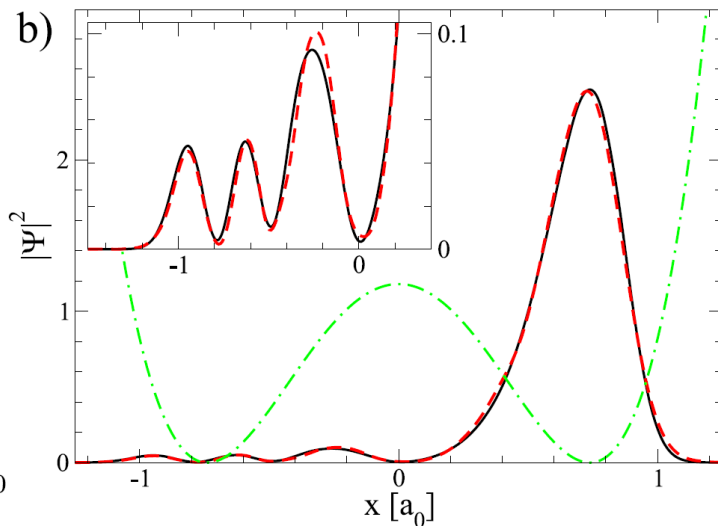
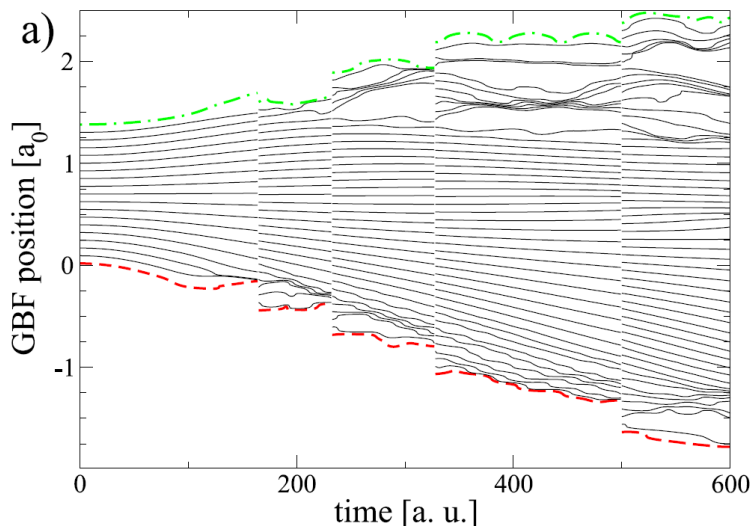


110 frozen width
111^c adapt corr
111 adapt uncor

(a_{11} , a_{12} , a_{22}) = solid, dot-dash, dash

circles = SOFT

inversion of ammonia model



1D $N_b=15-60$

WF $t=2000$ au

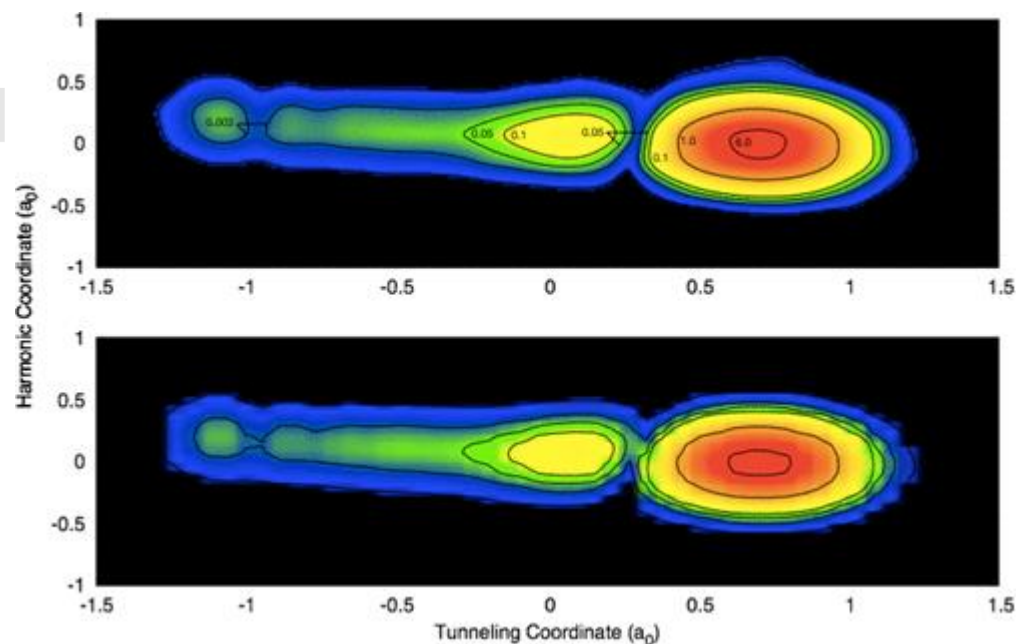
$V_b=22.5$ kJ/mol

WF energy $V_b/3$

1D energy levels

level	fixed-grid [E_h]	QTAG [E_h]
0^+	2.295×10^{-3}	2.295×10^{-3}
0^-	2.298×10^{-3}	2.297×10^{-3}
1^+	6.348×10^{-3}	6.348×10^{-3}
1^-	6.504×10^{-3}	6.503×10^{-3}

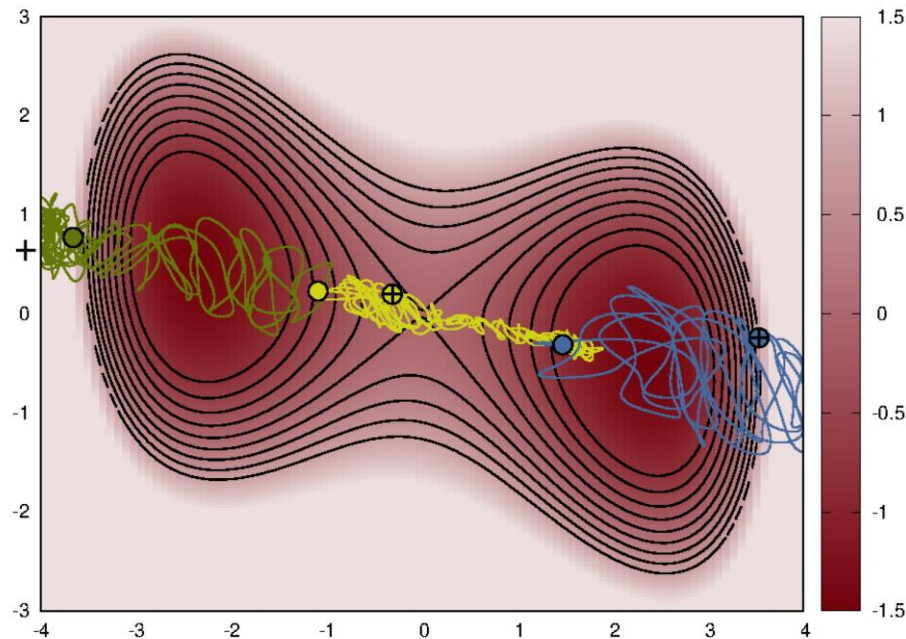
2D $N_b=103-269$ WF at $t=800$ au
QTAG(top) and SOFT (bottom)



tunneling dynamics with semiclassical bath

model I

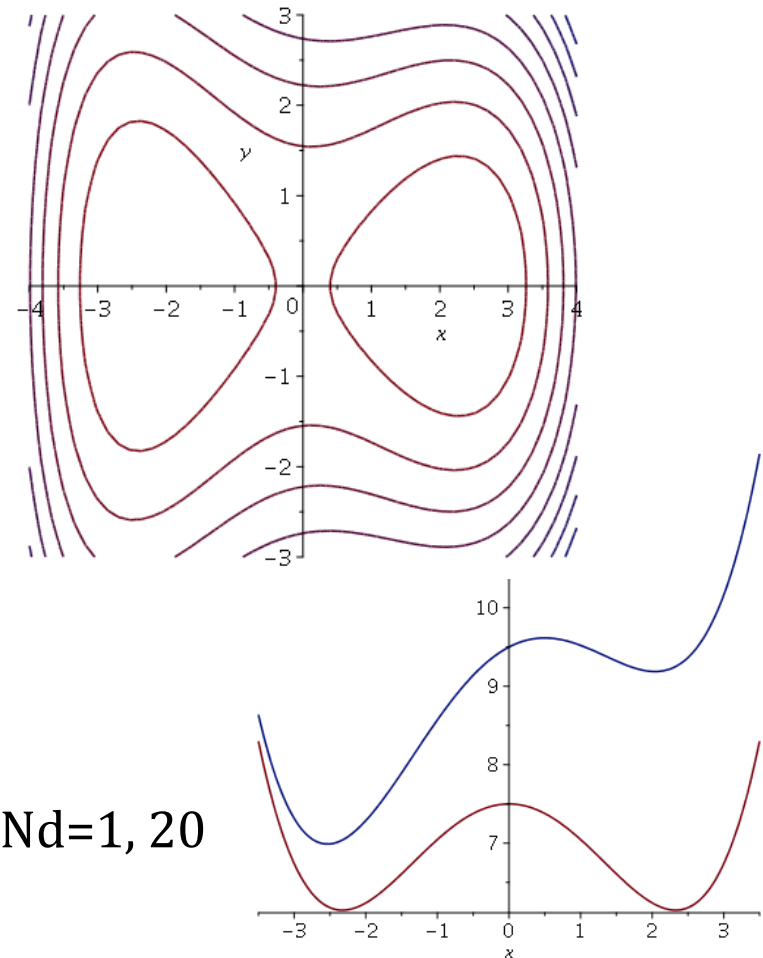
$$V^{\text{I}} = \frac{x_1^4}{16\eta} - \frac{x_1^2}{2} + c \sum_{\nu=2}^{N_d} x_{\nu-1} x_{\nu} + \sum_{\nu=2}^{N_d} \frac{x_{\nu}^2}{2}$$



Bath modes increase the
barrier $\sim 15\%$

model II

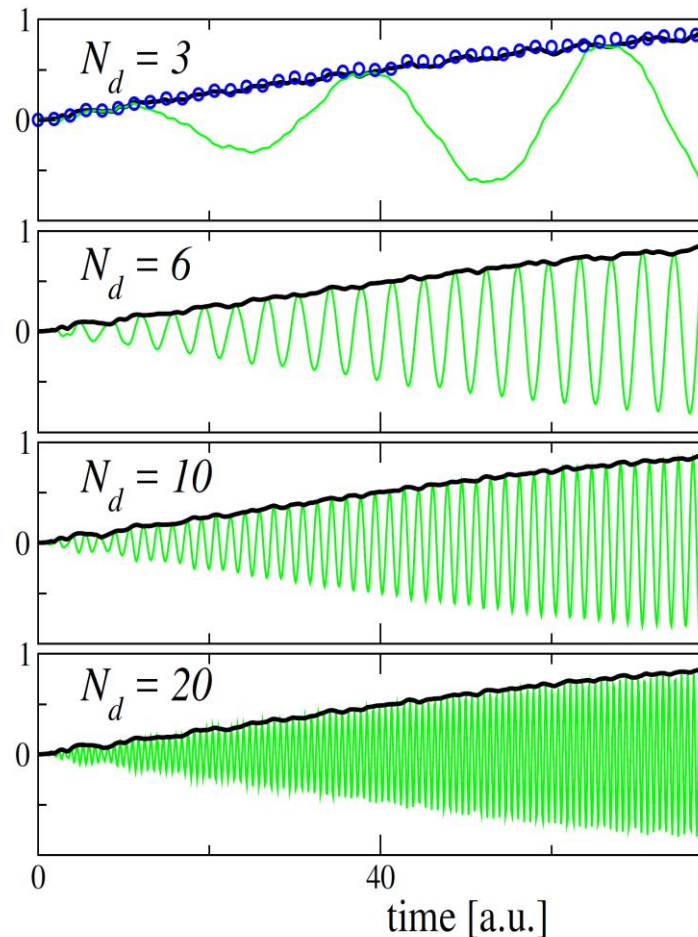
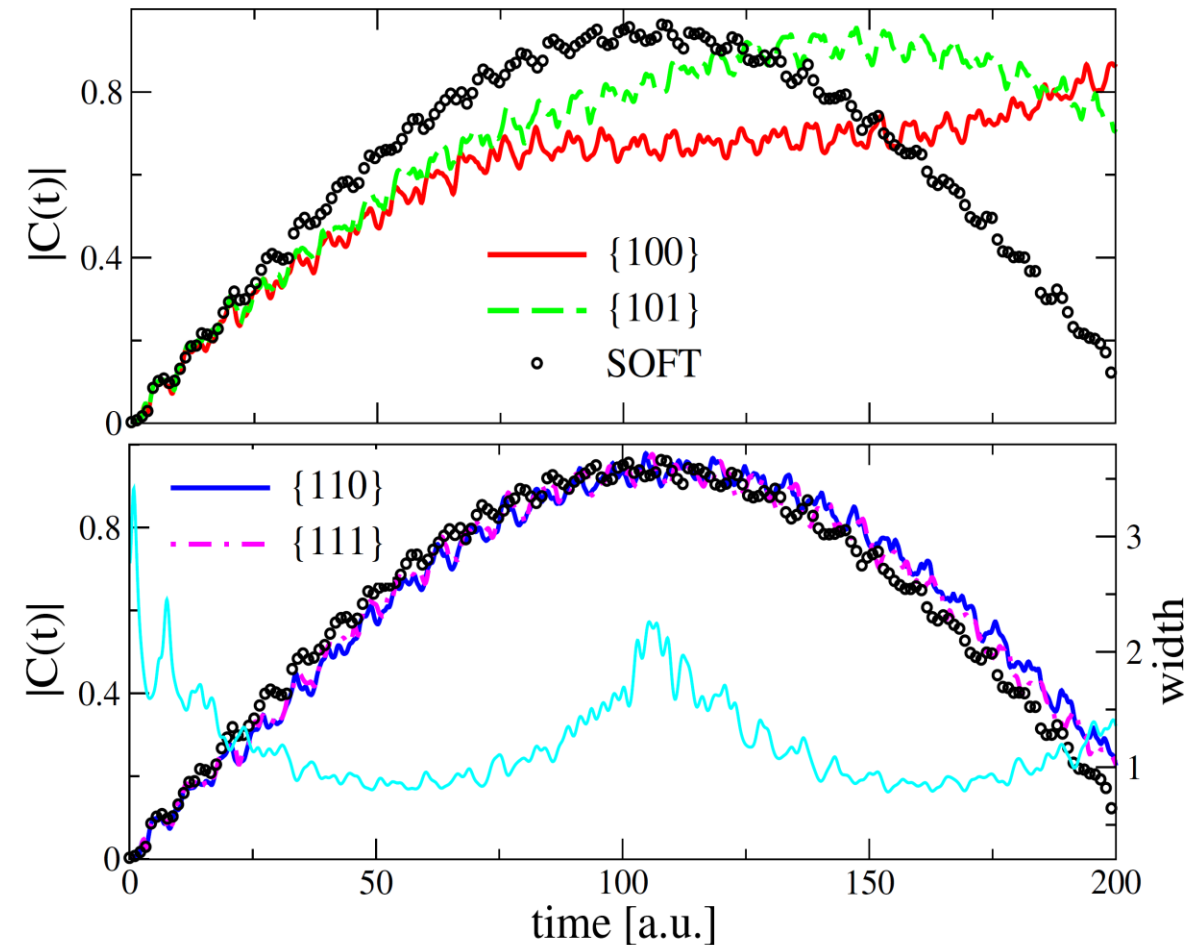
$$V^{\text{II}} = \frac{x_1^4}{16\eta} - \frac{x_1^2}{2} + \frac{c}{2} \sum_{\nu=2}^{N_d} x_1 x_{\nu}^2 + \sum_{\nu=2}^{N_d} \frac{x_{\nu}^2}{2}$$



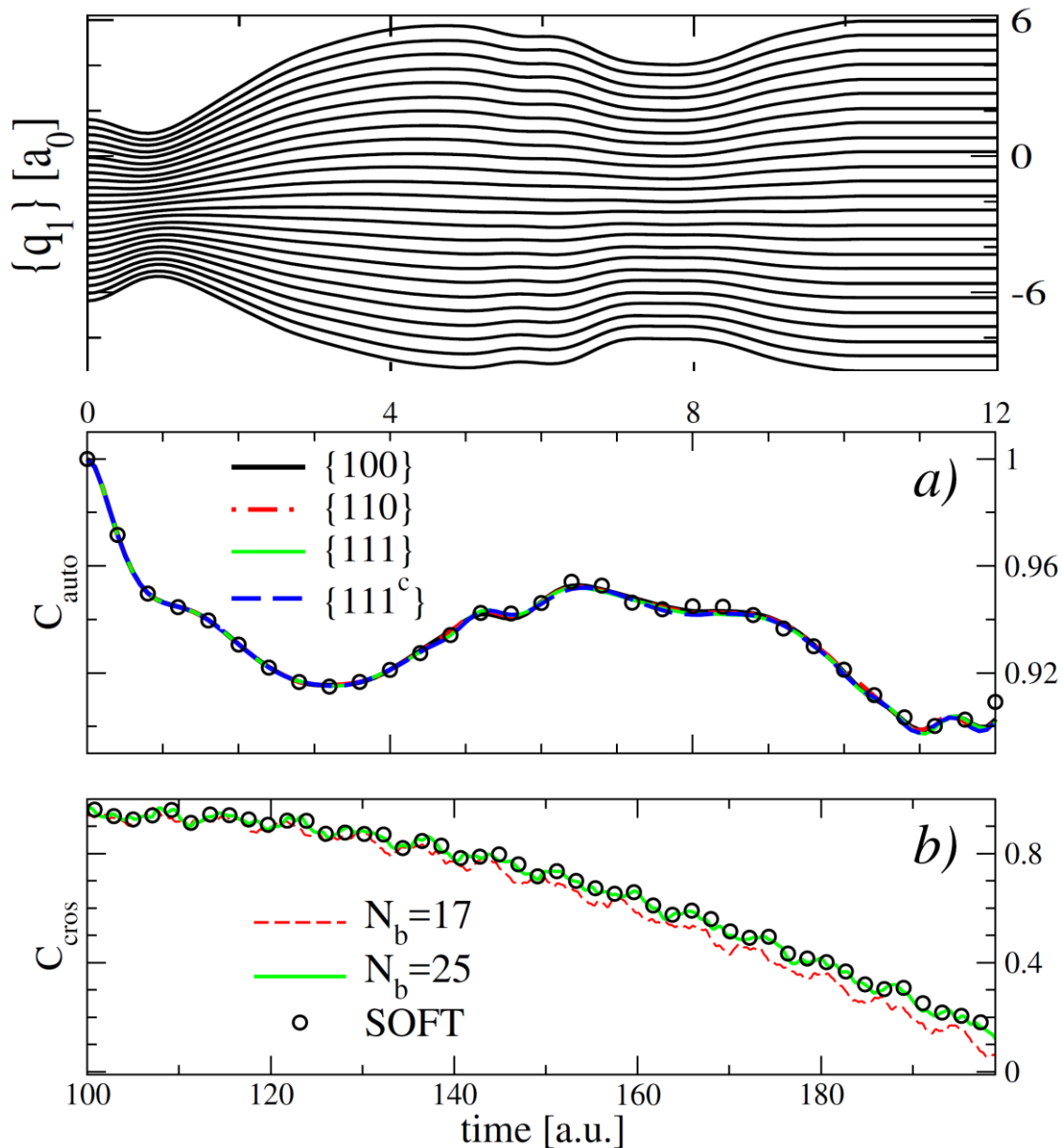
$N_d=1, 20$

model I: cross-correlation functions

single function per bath DOFs



(left) $N_d = 2$: 25 GBFs with four types $\{q,p,a\}$ of basis adaptability. The GBF width $a_1(t)$ for $\{111\}$ basis is on the bottom panel; vertical axis is on rhs. (right) $\{110\}$ basis is used



model I in 2D

correlated QTAG

(i) more flexible GBFs
improve accuracy

(ii) and they can be
stopped

thawed GBFs

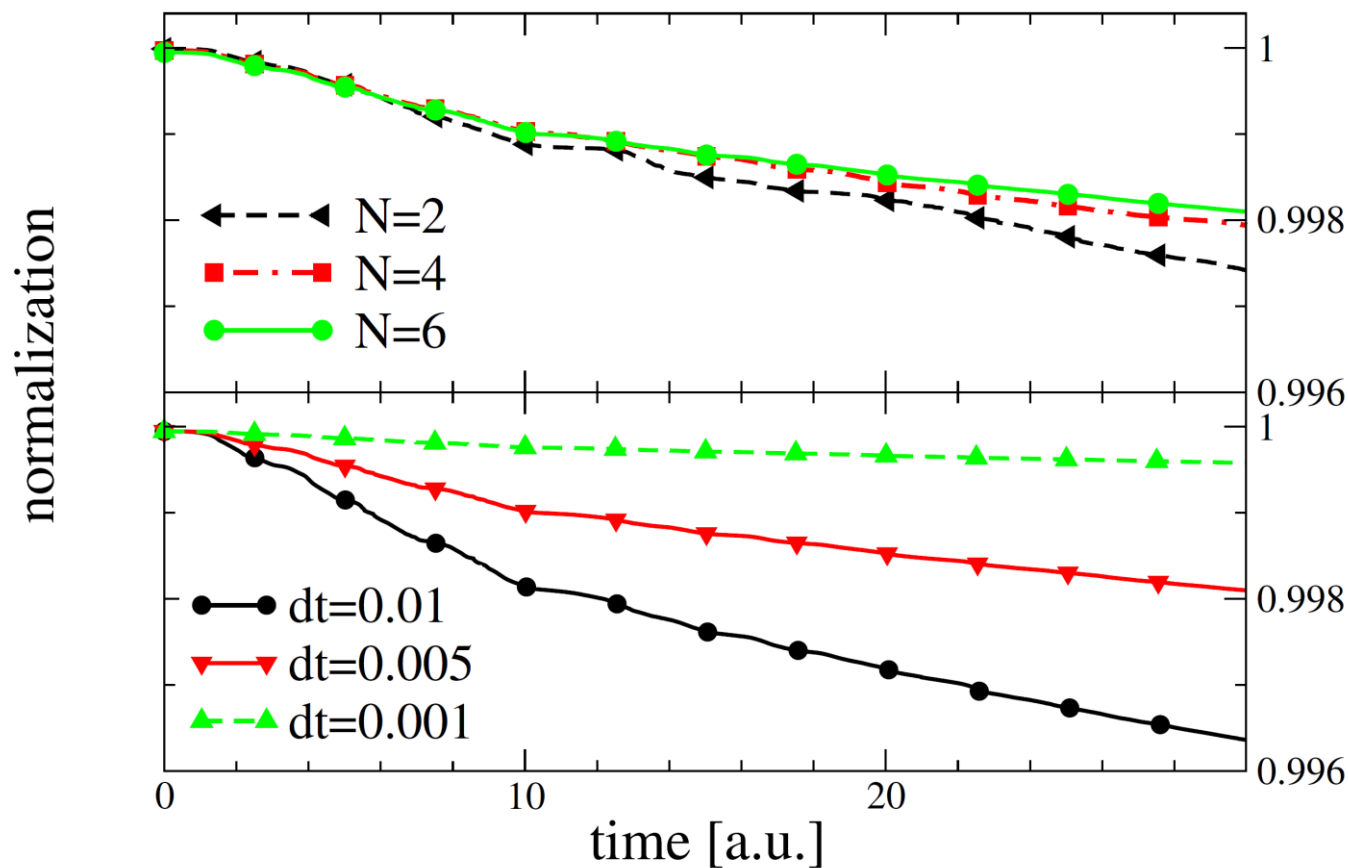
for bath DOFs?

(a) C_{auto} with four basis types of 25 GBFs

(b) C_{cros} with fully adaptable $\{111^c\}$

model I

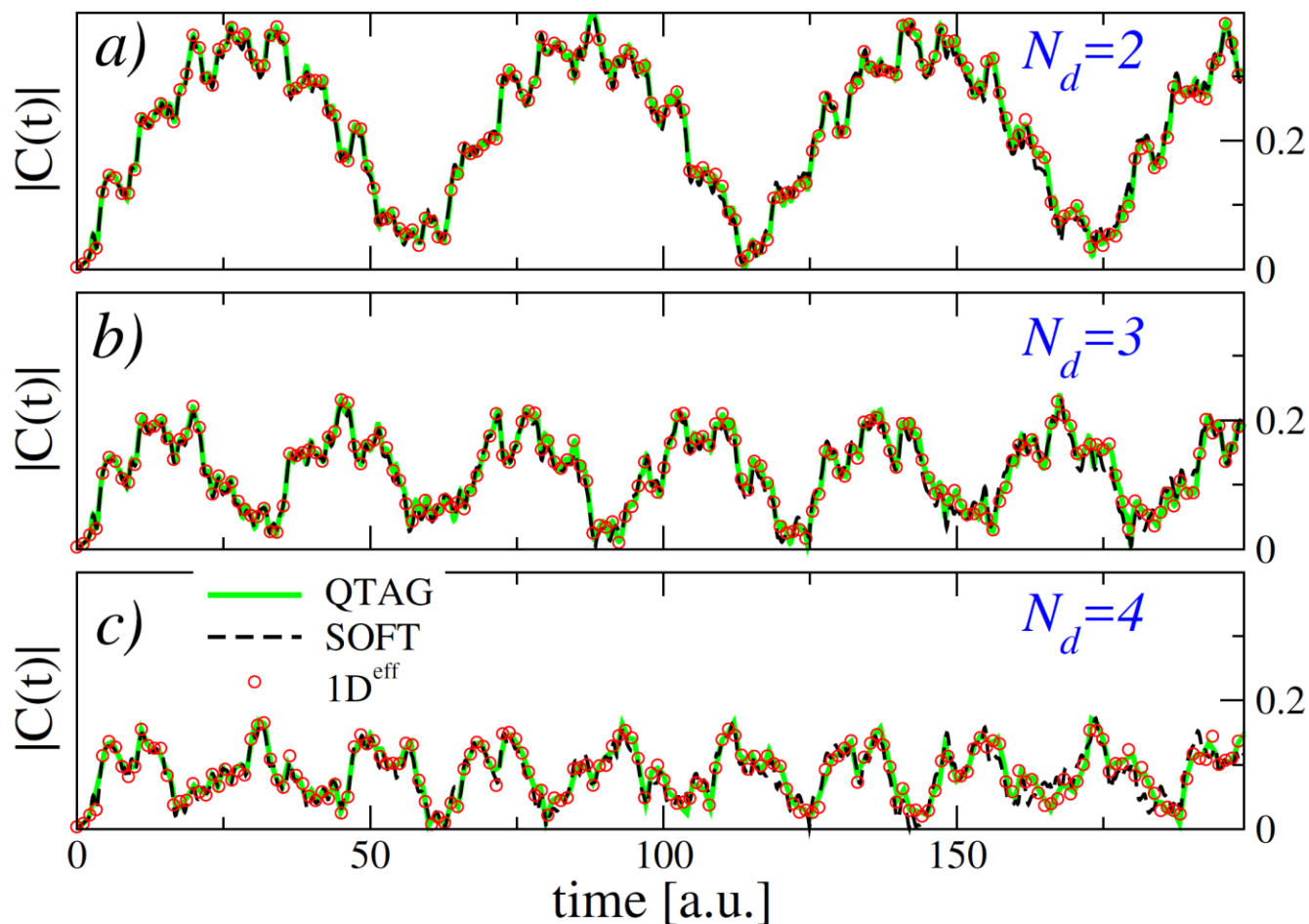
normalization conservation for 2,4,6 dimensions(top) and as a function of timestep for $N_d=6$ (bottom) with 'diagonalize/project' scheme



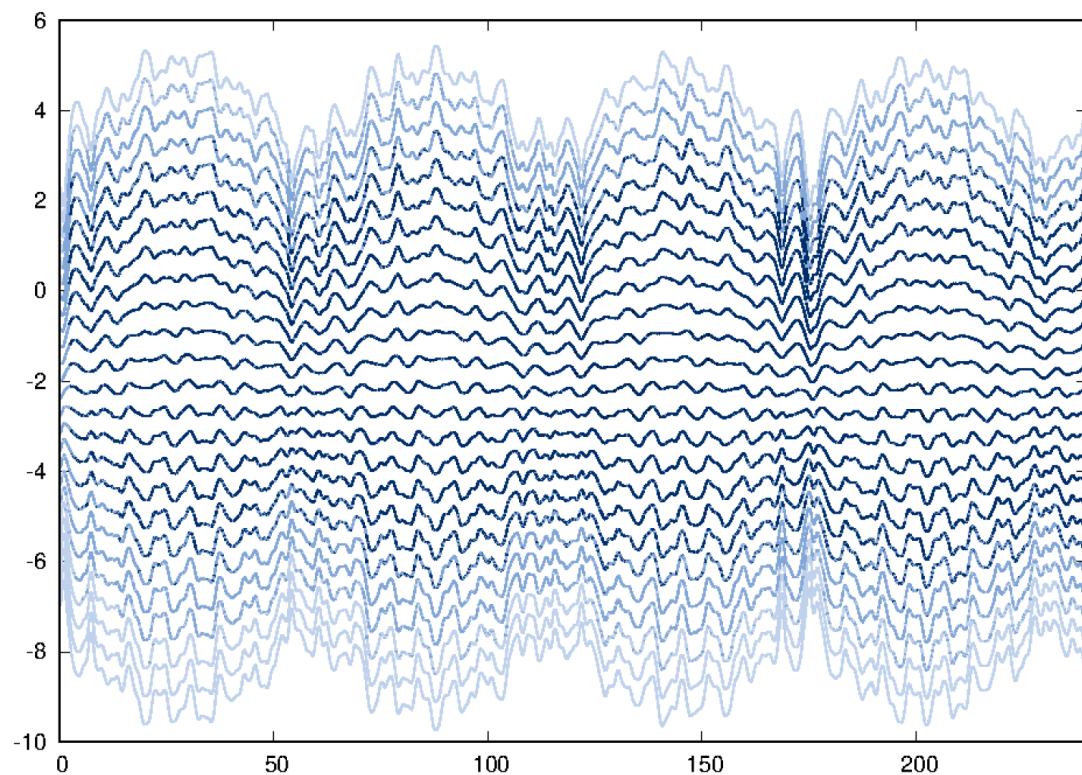
better propagators?

model II (nonlinear coupling, trajectories 'do not go' across the barrier)

effective potential $\tilde{V}_{N_d} = \frac{x_1^4}{16\eta} - \frac{x_1^2}{2} + \tilde{c}x_1 + V_0, \quad \tilde{c} = c \frac{N_d - 1}{2}, \quad V_0 = \frac{N_d - 1}{2}$



C_{cros} from QTAG (25 GBFs), SOFT in full D, and in 1D with effective potential



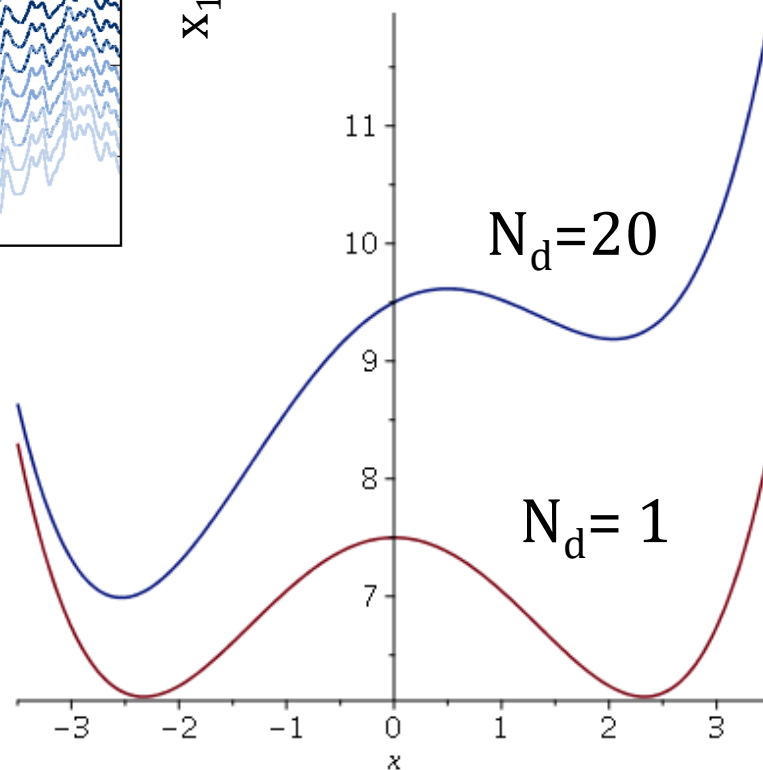
time [au]

well-to-well dynamics disappears
with N_d

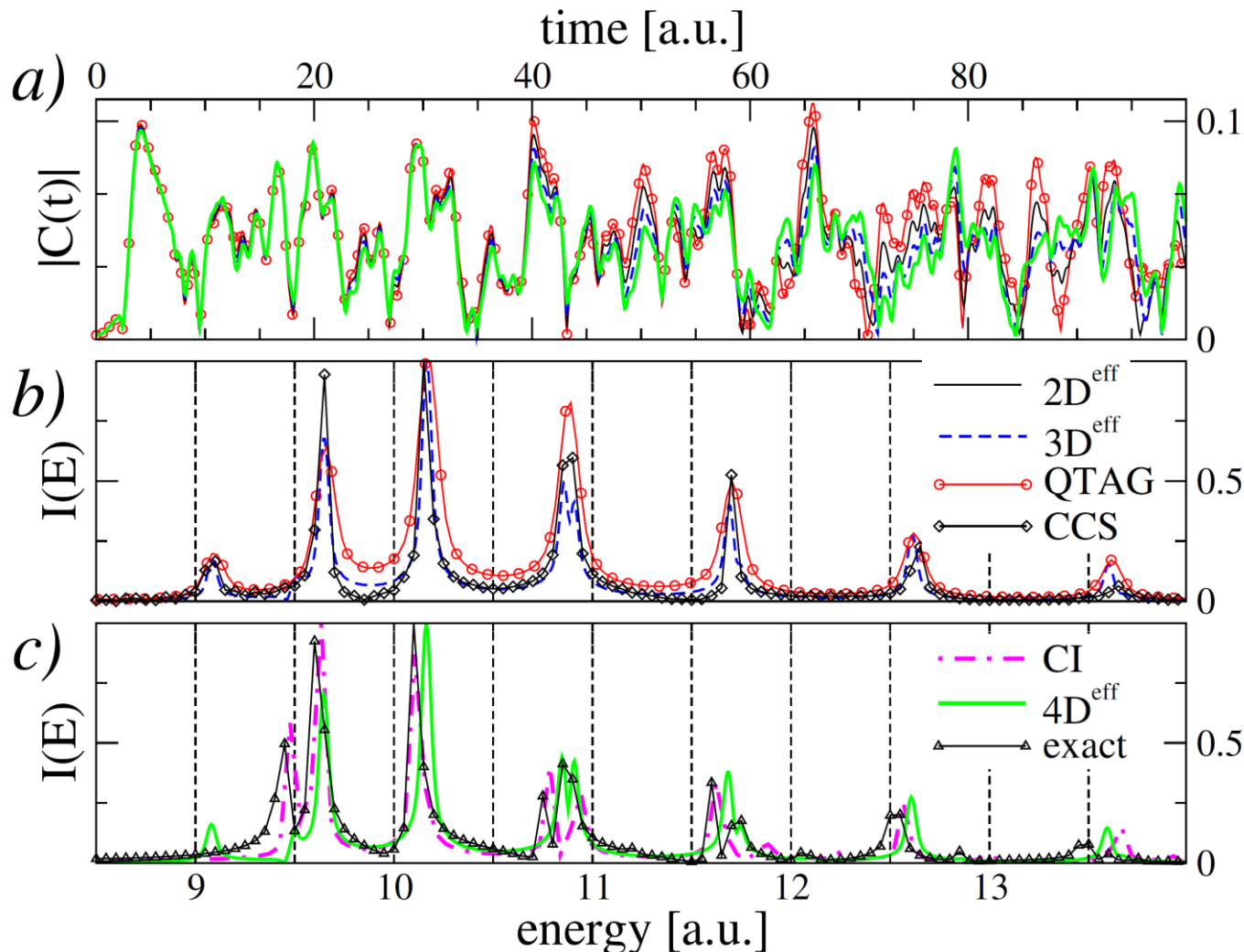
model II

the color intensity correlates
with the amplitudes of the
respective GBFs

x_1 [au]



model II single function per bath DOFs $N_d = 20, N_b = 40$



peaks split due
to bath DOFs

(a) C_{cross} from QTAG, SOFT and effective potentials

(b,c) The spectra compared to CCS, trajectory-guided CI and full basis.

Habershon JCTC 13 (2017), Shalashilin Chem. Phys. 322 (2006) & CPL 641 (2015)

summary

- QTs define compact WF representations for exact, approximate, mixed quantum dynamics
- QT-guided adaptable Gaussians are efficient and compatible with semiclassical representation of bath modes
- linear-in-x phase is important, GBF width adaptation is limited by LHA (V_{ij} evaluations); issues of stability and (re)expansions
- Need a general criterion to balance stationary and time-dependent representations based on broad features of WF

Thank you!

Bing Gu (UC Irvine)

Matt Dutra

Sachith Wickramasinghe



Propagation using energy eigenstates

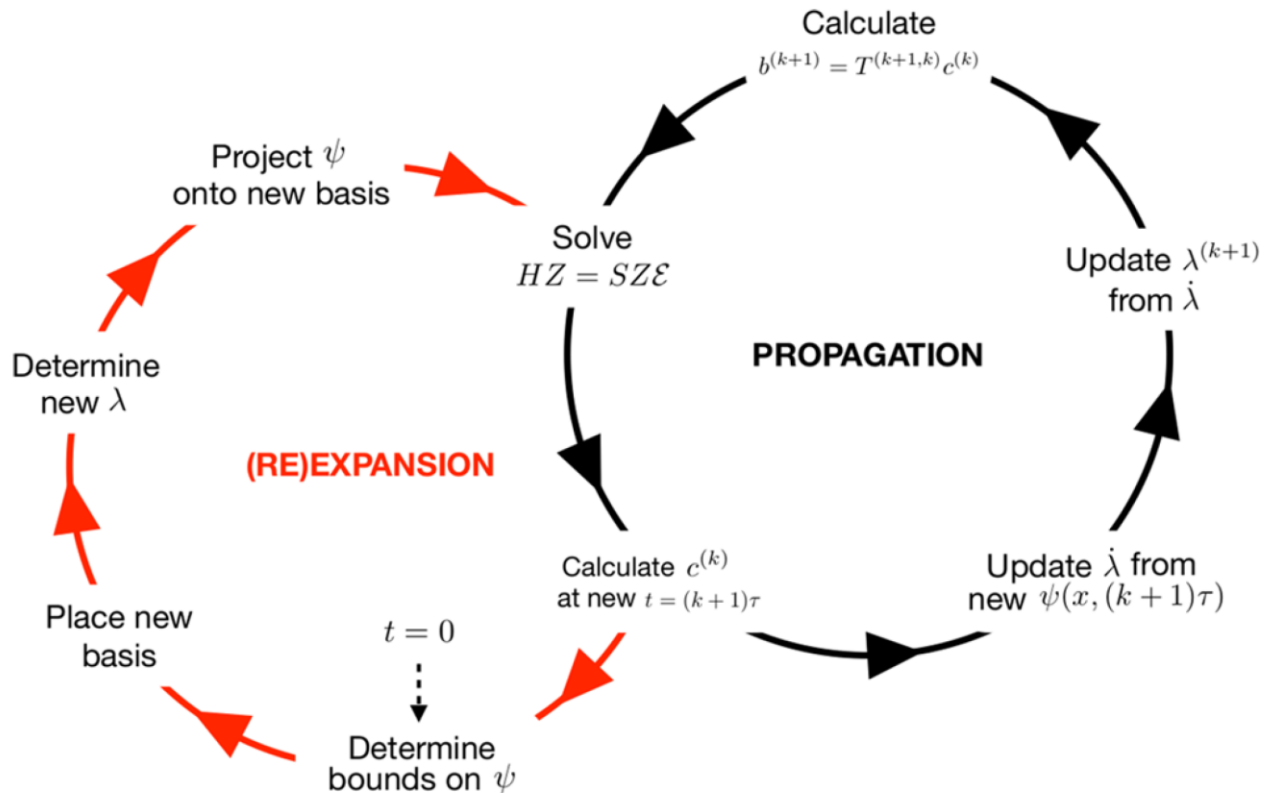
$$\psi(x, t_K) = \prod_{k=0}^{K-1} \vec{g}_{K-1} \mathbf{Z}_{K-1} e^{-i\Lambda_K(t_K - t_{K-1})} \mathbf{Z}_{K-1}^\dagger \mathbf{T}_{K-1, K-2} \dots \mathbf{T}_{1,0} \mathbf{Z}_0 e^{-i\Lambda_0(t_1 - t_0)} \mathbf{Z}_0^\dagger \vec{b}_0(t_0)$$

start	solve $\mathbf{HZ} = \mathbf{SZ}\mathbf{\Lambda}$	$\mathbf{H}, \mathbf{S}, t$	diagonal $\mathbf{\Lambda}, \mathbf{Z}, \mathbf{S}^{-1} = \mathbf{Z} \cdot \mathbf{Z}^\dagger, \mathbf{Z}^\dagger \mathbf{SZ} = \mathbf{I}$
(i)	propagate by τ	\vec{b}, \vec{c}	$\vec{c}(t + \tau) = \mathbf{Z} \exp(-i\mathbf{\Lambda}\tau) \mathbf{Z}^\dagger \vec{b}(t), \vec{b}(t) = \mathbf{S} \vec{c}(t)$
(ii)	define new basis	\vec{g}_{old}	$\vec{g}_{new}, \mathbf{H}_{new}, \mathbf{S}_{new}$
(iii)	solve $\mathbf{HZ} = \mathbf{SZ}\mathbf{\Lambda}$	$\mathbf{H}_{new}, \mathbf{S}_{new}$	new $\mathbf{\Lambda}, \mathbf{Z}, \mathbf{S}^{-1}$
(iv)	transform ψ to \vec{g}_{new}	$\vec{b}, \vec{c}, \vec{g}_{new}, \vec{g}_{old}$	$\vec{b}_{new} = \langle \vec{g}_{new} \otimes \vec{g}_{old} \rangle \vec{c}_{old}, \vec{c}_{new} = \mathbf{S}_{new}^{-1} \vec{b}_{new}$
(v)	“observables”	$\vec{c}, \vec{g}, \mathbf{H}, \mathbf{S}$	$\psi(x, t) = \vec{g}^T(x) \cdot \vec{c}(t), \langle \psi \hat{H} \psi \rangle = \vec{c}^\dagger \mathbf{H} \vec{c}$
(vi)	relabel <i>new</i> as <i>old</i> and $t + \tau$ as t		continue to (i) or stop

Conservation of the norm and energy depends on the basis completeness

$$\langle \psi | \hat{H} | \psi \rangle = \vec{c}_1^\dagger \mathbf{H}_1 \vec{c}_1 = \vec{c}_0^\dagger \langle \vec{g}_0 | \mathbb{I}_1 \hat{H} \mathbb{I}_1 | \vec{g}_0^T \rangle \vec{c}_0 \approx \vec{c}_0^\dagger \mathbf{H}_0 \vec{c}_0 \quad \mathbb{I}_1 = |\vec{g}_1\rangle \mathbf{S}_1^{-1} \langle \vec{g}_1|$$

Time evolution algorithm: (left) steps of the expansion, or reexpansion, of a wave function in a basis; (right) time propagation with basis orthogonalization and transformations (BOT). A simulation begins at the $t = 0$ label, completes the left (red) loop, and propagates along the right (black) loop until a reexpansion criterion is met at which point the (re)expansion branch is again taken or the simulation completes. See text for the reexpansion criteria.



Approximate Quantum Potential & Force

- Use a **small basis** ($x, y, \dots, 1$) to approximate the **nonclassical** momentum

$$r := \frac{\nabla A(x, t)}{A(x, t)} \quad \text{where} \quad A = |\psi|$$

- Variationally determined quantum potential: the WF energy is conserved
 - Linear in x basis is exact for a Gaussian wavepacket
 - Mean-field like, resembles Hartree-Fock
 - Infinite basis gives exact QM (like full CI)
-
- Discretize WF in terms of a trajectory ensemble
 - Evolve QTs under the sum of classical and quantum forces
 - Expectation values are simple ensemble averages